

Heat transfer model for small-scale air-cooled spark-ignition four-stroke engines

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Received 18 January 2006; received in revised form 1 March 2006

Available online 27 June 2006

Abstract

The heat transfer models proposed in previous studies are not suitable for small-scale spark-ignition engines, because they were developed primarily for large-scale engines. In order to improve the accuracy of the predicted heat transfer rate for small-scale engines, a heat transfer model using the Stanton number is proposed in this paper. Prediction results of instantaneous heat flux, global engine heat transfer, and cylinder pressure based on the proposed model are compared with the experimental results and prediction results of previous models. It is found that the proposed model has prediction results closer to the measured data than the previous models at most engine operating conditions.

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Keywords: Engine heat transfer model; Stanton number; Spark-ignition engine; Heat flux

1. Introduction

The heat transfer model can be used to predict the engine heat transfer rate, which is very important for thermal load analysis, combustion performance prediction, and cycle simulation. Most investigations of heat transfer in spark-ignition (SI) engines are large-scale ones. Oguri [1] used Eichelberg's model to predict the heat transfer rate of a 1400 cm³ SI engine, yielding predicted results that agreed with the experimental results for the expansion stroke, but not for the compression stroke. This might be because the model was established for diesel engines and was not suitable for SI engines. Alkidas [2,3] measured the instantaneous heat flux on the cylinder head of an 820 cm³ four-stroke SI engine and found that it could be affected by the engine speed, air–fuel ratio, and volumetric efficiency. Alkidas and Suh [4] investigated the effects of swirl or tumble motion on the heat transfer and combus-

tion characteristics of a single-cylinder four-valve 400 cm³ SI engine. It was found that increasing swirl or tumble motions might raise the peak rate of heat release, the local surface temperature, and heat flux, on the cylinder head. Shayler [5] utilized two methods to obtain the instantaneous heat flux of the combustion chamber. In the first method, the first law of thermodynamics was applied to calculate the heat transfer rate, but the results were not accurate due to uncertain gas properties. In the second method, the heat transfer rates were calculated based on Woschni's, Annand's, and Eichelberg's experimental models. It was found that Eichelberg's model could produce prediction results closest to the experimental data.

Previous studies have focused on developing heat transfer models for large-scale engines. However, the heat transfer characteristics of large-scale and small-scale engines are quite different. For large-scale SI engines, about one-third of the fuel energy is transformed to heat loss from the cylinder body. But for a small-scale 125 cm³ two-stroke SI engine, Franco [6] found that approximately 50% of the fuel energy is converted to heat loss, which is much higher than that of large-scale SI engines. Since the heat transfer

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Nomenclature

Notation

A	area of the heat absorbing surface (m ²)
A_n, B_n	Fourier coefficients (dimensionless)
B	bore diameter (m)
C_m	mean piston speed m/s
c	specific heat (J/kg K)
EOC	end of combustion (deg)
h	heat transfer coefficient (W/m ² K)
k	thermal conductivity (W/m K)
m	mass (kg)
MFB	mass fraction burned (%)
N	total harmonic number (dimensionless)
n	harmonic number (dimensionless)
P	pressure (N/m ²)
Q	heat (J)
R	gas constant (kJ/kg K)
Re	Reynolds number (dimensionless)
SOC	start of combustion (deg)
St	Stanton number (dimensionless)
T	temperature (K)
t	time (s)
u	turbulent fluctuating velocity (m/s)
V	volume (m ³)
x	distance (m)
α	thermal diffusivity (m ² /s)
γ	the ratio of specific heats (dimensionless)
ε	emissivity (dimensionless)
η_v	volumetric efficiency (dimensionless)

θ	crank angle (deg)
θ_0	start of combustion timing (deg)
θ_d	total combustion duration (deg)
μ	dynamic viscosity (kg/m s)
ρ	density (kg/m ³)
τ	time period of the temperature (s)
ω	angular speed (rad/s)

Subscripts

ai	airflow into the intake manifold
ao	airflow out of the intake manifold
conv	convective
cyl	cylinder
cc	combustion chamber
d	displacement
e	engine
f	fuel
g	gas
HV	heating value
ht	heat transfer
hr	heat release
im	intake manifold
m	mean value
p	piston or constant pressure
r	radiant
sp	spark plug
w	wall

characteristics of small-scale engine are different from that of large-scale engine, it is important to develop a heat transfer model specific for four-stroke small-scale SI engines.

This paper studies the heat transfer characteristic of a 125 cm³ air-cooled four-stroke SI engine, and develops a corresponding heat transfer model. The remainder of this paper is organized as follows. Section 2 introduces previous heat transfer models. The heat flux obtained from the measured temperatures is then used to establish the heat transfer model in Section 3. The heat transfer model is used for engine simulation and the engine model is described in Section 4. Simulation results of cylinder pressure are compared with the experimental results in Section 5. Finally, conclusions are made in Section 6.

2. Modeling of the heat transfer coefficient

The heat transfer rate \dot{Q}_{ht} from the flowing gas to the combustion chamber wall is dominated by the forced convection [7,8] and can be expressed as

$$\frac{d\dot{Q}_{ht}}{dt} = h \cdot A \cdot (T_g - T_w) \quad (1)$$

where A is the area of the heat transfer surface, which is often defined as the entire surface of the combustion chamber [3,7,10,17]; h is the empirical heat transfer coefficients, which is assumed the same for the entire heat transfer surface; T_w is the measured temperature of the inside wall surface of the combustion chamber; and T_g is the temperature of the flowing gas, which can be obtained using the state equation of ideal gas [1,9–13] as follows:

$$T_g = \frac{P_{cyl} \cdot V_{cyl}}{m_a \cdot R} \quad (2)$$

where P_{cyl} is the cylinder gas pressure, V_{cyl} is the cylinder volume, m_a is the air mass in the cylinder, and R is the gas constant.

Many models have been proposed for the heat transfer coefficient h assuming that the heat flux is the same for the entire heat transfer surface. Several previous models and the proposed model will be applied to obtain the curve fitted heat transfer coefficient h for the target engine.

2.1. Previous models

Nusselt's model was the first engine heat transfer model based on a spherical bomb, originally it was used to predict

the steady-state heat flux. It can also be used to predict the instantaneous heat flux, if it is expressed in terms of instantaneous P_{cyl} and T_{g} [15,16] as

$$h = h_c + h_r \quad (3)$$

where h_c and h_r are the heat transfer coefficients for convection and radiation, respectively, and can be expressed as

$$h_c = a \cdot (1 + 1.24C_m) \cdot (P_{\text{cyl}}^2 \cdot T_{\text{g}})^{\frac{1}{3}}, \quad \text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (4)$$

$$h_r = \frac{4.21 \times 10^{-4}}{(1/\varepsilon_g + 1/\varepsilon_w - 1)} \frac{(T_{\text{g}}/100)^4 - (T_w/100)^4}{(T_{\text{g}} - T_w)},$$

$$\text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (5)$$

where a is a curve fitted constant, which can be obtained from the experimental data; C_m is the mean piston speed (m/s); ε_g is gas emissivity and ε_w is wall emissivities.

Eichelberg's model has been widely used to study the heat transfer in large-scale two-stroke and four-stroke diesel engines [11] and can be expressed as

$$h = a \cdot (C_m)^{1/3} \cdot (P_{\text{cyl}} \cdot T_{\text{g}})^{1/2}, \quad \text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (6)$$

Annand proposed a heat transfer model based on the steady-state turbulent convection [9,15], as follows:

$$h = a \cdot \frac{k}{B} \cdot Re^{0.7} + b \cdot \frac{(T_{\text{g}}^4 - T_w^4)}{(T_{\text{g}} - T_w)}, \quad \text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (7)$$

where k is the thermal conductivity of the fluid; B is the diameter of the engine bore; and a is a curve fitted constant ranging from 0.35 to 0.8 depending on the intensity of charge motion. The constant b is suggested to be 4.3×10^{-12} for SI engines. Re is the Reynolds number, which can be expressed as

$$Re = \frac{\rho \cdot C_m \cdot B}{\mu} \quad (8)$$

where ρ is the gas density and μ is the dynamic gas viscosity.

Sitkei's model is used to study the heat transfer in four-stroke indirect injection diesel engines and can be expressed as [15]

$$h = a \cdot (1 + b) \frac{P_{\text{cyl}}^{0.7} \cdot C_m^{0.7}}{T_{\text{g}}^{0.2} \cdot (4V_{\text{cyl}}/A)^{0.3}}, \quad \text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (9)$$

where V_{cyl} is the cylinder volume. The dimensionless constant b , which ranges from 0 to 0.35 depending on the type of combustion chamber [7], is used for additional turbulent velocity.

Hohenberg studied the heat transfer for six engines type and proposed a model [10], as follows:

$$h = a \cdot V_{\text{cyl}}^{-0.06} \cdot P_{\text{cyl}}^{0.8} \cdot T_{\text{g}}^{-0.4} \cdot (C_m + 1.4)^{0.8}, \quad \text{unit} = \frac{\text{kW}}{\text{m}^2\text{K}} \quad (10)$$

where P_{cyl} has the unit of bar.

2.2. Proposed model

In order to provide a simple heat transfer model, but yet accurate enough, for the engine simulation, a heat transfer coefficient using the Stanton number St is proposed in this paper, as follows:

$$h = St \cdot \rho \cdot c_p \cdot u \quad (11)$$

where u is the gas turbulent fluctuating velocity, which can be approximated as $0.5C_m$ under the assumption of open combustion chamber without swirl [12]. The factor c_p is the specific heat at constant pressure, and can be expressed as

$$c_p = \frac{R}{1 - (1/\gamma)} \quad (12)$$

where γ is the specific heat ratio, which can be obtained using the following equation [20]:

$$\gamma = 1.338 - 6 \times 10^{-5}T_{\text{g}} + 10^{-8}T_{\text{g}}^2 \quad (13)$$

Since T_w is measured on the inside wall surface of the combustion chamber, it might change for different measured locations. In order to eliminate the location dependency, the spark plug temperature T_c is used to replace T_w for the proposed model in this paper.

The most heat energy is generated near the top-dead-center (TDC) and is transferred to the cylinder head surface and piston surface simultaneously. Woschni [18] and Yoo [19] studied the local heat transfer of the piston and cylinder head, and found that about 55% of the heat energy is transferred to the piston and about 45% of that is transferred to the cylinder head. Based on the results in [18,19], the area of heat transfer surface is defined as two times the piston area, i.e. $2A_p$, for obtaining global heat transfer rate.

3. Heat flux analysis

3.1. Experimental setup

A 125 cm³ four-stroke air-cooled spark-ignition engine with a single cylinder was employed for developing the heat transfer coefficient in this paper, with specifications as shown in Table 1. Five thermocouples were used to measure the temperatures of the cylinder head at specific positions, as shown in Fig. 1. Two E-type coaxial thermocouples (Medtherm TCS-102-E), th_1 and th_2 , were used to measure the instantaneous temperatures of the inside surface of the cylinder wall near the exhaust and intake valves, respectively. Two K-type thermocouples with Omega 650 temperature indicator, th_3 and th_4 , were used to measure the steady-state temperatures of the outside surface of the cylinder wall near the exhaust and intake valves, respectively. Another K-type thermocouple, th_{sp} , was used to measure the temperature of the spark plug T_{sp} . The mean cylinder gas temperature T_{g} was estimated using the state equation of ideal gas as shown in Eq. (2) with the cylinder

Table 1
Specifications of the target engine

Engine model	Suzuki AN125
Engine type	Four-stroke, air cooled, OHC
Bore × stroke	52 × 58.6 mm
Fuel system	Carburetor
No. of valves	2
Displacement volume	125 cm ³
Compression ratio	10.2
Idle speed	1800 rpm
Ignition Type	CDI
Spark advance	5°/1500 rpm, 26°/4500 rpm
Cylinder head material	Aluminum alloy
Combustion chamber	Hemisphere-shaped

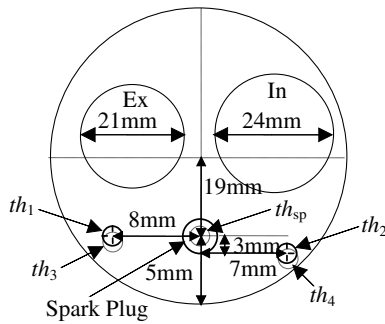


Fig. 1. Inside view of the locations of thermocouples on the cylinder head.

pressure, which was measured with the spark-plug type pressure transducer (Kistler 6117A37).

In order to obtain the engine heat transfer rate for a wide-range of operating conditions, the engine speed was adjusted from 3000 to 6000 rpm at increments of 1000 rpm, and the brake mean effective pressure (BMEP) used as the engine load was adjusted from 1 to 7 bar with an increment of 1 bar.

3.2. Heat flux calculation

In most heat flux calculation, the heat flux through the cylinder head wall is assumed to be one-dimensional unsteady heat conduction [1,4,7,9,15]. Since the unsteady heat conduction of the in-wall temperature field exists only within a very small distance from the wall surface, the unsteady component of the temperature gradient perpendicular to the surface is usually much larger than that parallel to the surface. Therefore, one-dimensionality is safely assumed for the unsteady component of the surface heat flux calculation [15]. The heat flux at the combustion chamber can be obtained by solving the following partial differential equation with two boundary conditions.

$$\frac{\partial T}{\partial t} = \alpha \frac{\partial^2 T}{\partial x^2} \quad (14)$$

where T is the temperature of the cylinder wall, which is a function of t and x ; t is the time; x is the distance from the

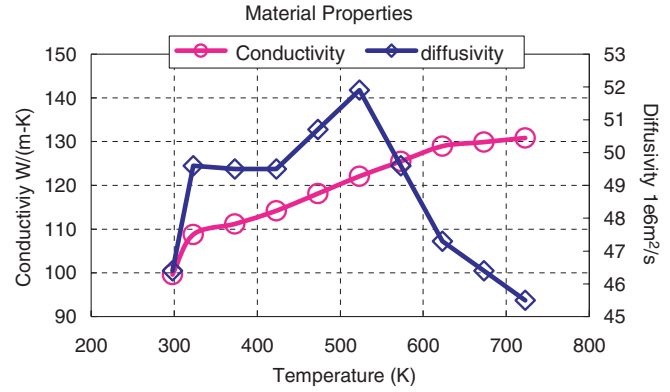


Fig. 2. Material thermal properties [21].

wall surface; $\alpha = k/\rho c$ is the thermal diffusivity; k is the thermal conductivity; and c is the specific heat. The boundary conditions are defined as follows:

$$\begin{aligned} T(0, t) &= T_{wi}(t) \quad \text{at } x = 0 \\ T(\ell, t) &= T_{wo}(t) = \text{constant} \quad \text{at } x = \ell \end{aligned} \quad (15)$$

where T_{wi} is the instantaneous temperature of the cylinder inside wall surface and T_{wo} is the steady-state temperature of the cylinder outside wall surface with a distance ℓ from the inside wall surface. The material properties of the cylinder head with k and α are functions of temperature [21], as shown in Fig. 2.

First, T_{wi} is represented by the following Fourier series [14]:

$$T_{wi} = T_{wm} + \sum_{n=1}^N [A_n \cos(n\omega t) + B_n \sin(n\omega t)] \quad (16)$$

where T_{wm} is the time-averaged value of T_{wi} ; ω is the angular frequency of temperature variation, which is one half of the engine angular velocity for the four stroke engine; and N is the harmonic number which is set to be 200 in this paper.

The solution of Eq. (14) can be expressed as

$$T(x, t) = T_{wm} - (T_{wm} - T_{wo}) + \sum_{n=1}^{\infty} e^{-c_n x} F_n(x, t) \quad (17)$$

where

$$F_n = A_n \cos(n\omega t - c_n x) + B_n \sin(n\omega t - c_n x) \quad (18)$$

$$A_n = \frac{2}{\tau} \int_0^{\tau} T_w(t) \cos(\omega n t) dt \quad (19)$$

$$B_n = \frac{2}{\tau} \int_0^{\tau} T_w(t) \sin(\omega n t) dt \quad (20)$$

$$c_n = \sqrt{\frac{n\omega}{2\alpha}} \quad (21)$$

The instantaneous heat flux at the cylinder inside wall surface, i.e. $x = 0$, can then be obtained using Fourier's law, as follows:

$$\begin{aligned}
 q_w(t) &= -k \left(\frac{\partial T}{\partial x} \right)_{x=0} \\
 &= \frac{k}{\ell} (T_{wm} - T_{wo}) + k \sum_{n=1}^N c_n [(A_n + B_n) \cos(nc\omega t) \\
 &\quad + (B_n - A_n) \sin(nc\omega t)]
 \end{aligned}
 \tag{22}$$

Since the major heat flux is produced within compression and expansion strokes, q_w is calculated only for these two strokes. The measured temperatures of the cylinder inside wall surface at 6000 rpm with 7 bar BMEP are shown in Fig. 3. As can be seen from Fig. 3, the temperature near the exhaust valve $T_{wi,ex}$ is higher than that near the intake valve $T_{wi,in}$, because the exhaust valve region is heated by the high-temperature exhaust. Both $T_{wi,ex}$ and $T_{wi,in}$ have large temperature gradients near TDC due to the combustion. The corresponding instantaneous heat fluxes $q_{w,ex}$ and $q_{w,in}$ can then be calculated for the exhaust and intake valve regions, respectively, as shown in Fig. 4. The greater the temperature gradient, the higher the heat flux is.

Two instantaneous heat fluxes at the exhaust and intake valve regions are used to represent the average instantaneous heat flux q_m , i.e. $q_m = (q_{w,in} + q_{w,ex})/2$. Fig. 5 shows the experimental results with different load conditions at 6000 rpm. The instantaneous heat flux grows with increasing engine loads, because the gas heat transfer coefficient is increased with higher gas pressure and temperature [9,22]. Fig. 6 shows the experimental results with different engine speeds at 6 bar BMEP. Since the gas pressure and temperature do not vary significantly with the engine speed under constant load, the gas heat transfer coefficient changes only slightly with different engine speeds, as does the instantaneous heat flux.

3.3. Curve fitted heat flux

For the engine simulation, the heat transfer rate can be obtained using Eq. (1). Since the wall temperature,

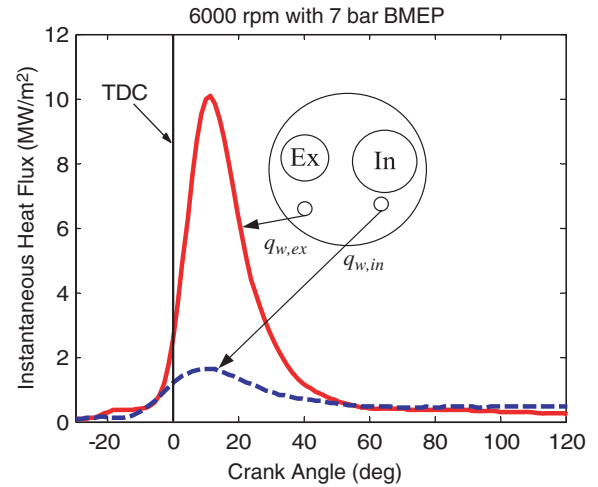


Fig. 4. Instantaneous heat flux variation of the cylinder inside wall surface.

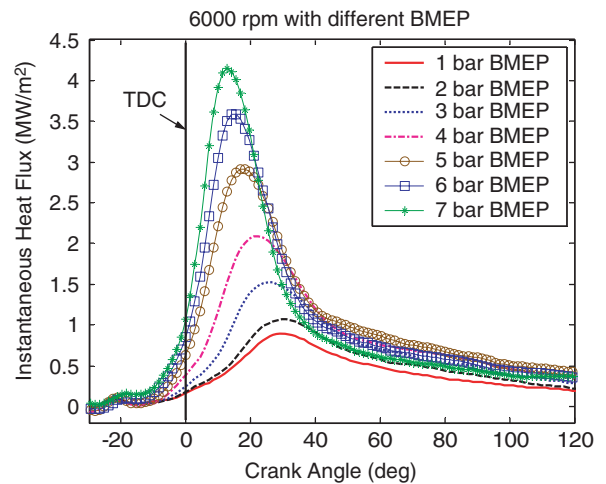


Fig. 5. Heat flux with different engine loads at 6000 rpm.

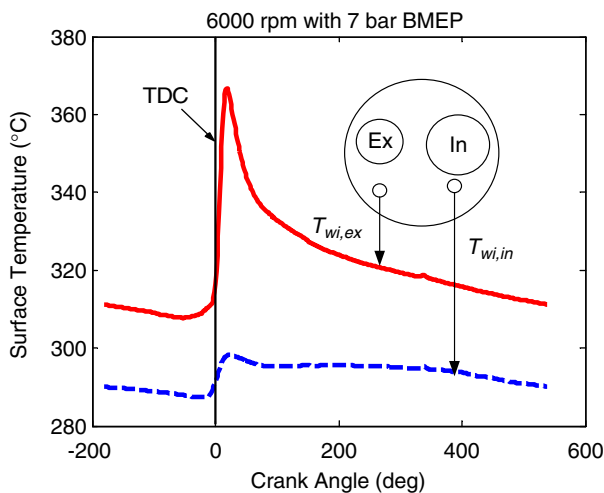


Fig. 3. Temperature variation of the cylinder inside wall surface.

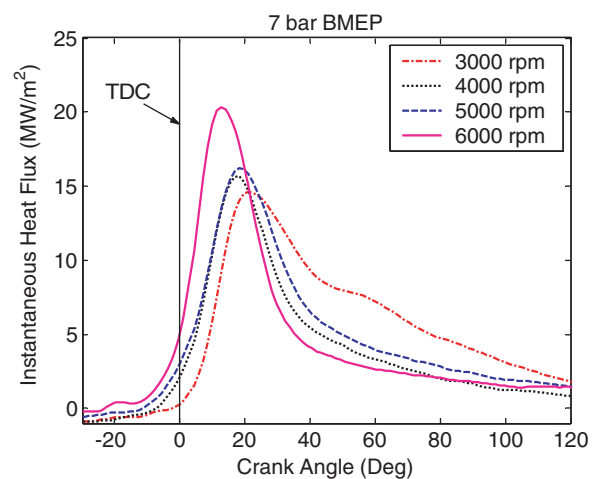


Fig. 6. Heat flux with different engine speeds at 6 bar BMEP.

T_w , varies with the crank angle, engine speed, and engine load, it is difficult to simulate the detailed T_w . Therefore, T_w is represented as an experimental formula for the compression and expansion strokes in this paper, which can be expressed as

$$T_w = a_{w1} - a_{w2} \cdot \omega_e + a_{w3} \cdot \omega_e^2 - a_{w4} \cdot P_m + a_{w5} \cdot P_m^2 + a_{w6} \cdot \omega_e \cdot P_m, \quad \text{unit} = ^\circ\text{C} \quad (23)$$

where ω_e is the engine speed with the unit of rev/second; P_m is the intake manifold pressure with the unit of bar; and a_{wi} is the coefficient obtained from the curve fitting of experimental results and is listed in Appendix 1; the coefficient of determination R_S is used to evaluate correlations between the measured and predicted values of R_S can be expressed as

$$R_S = \frac{\sum_{i=1}^n (\hat{y}_i - \bar{y})^2}{\sum_{i=1}^n (y_i - \bar{y})^2} \quad (24)$$

where y is the experimental data; \bar{y} is the mean value of experimental data; and \hat{y} is the predicted data. Here, R_S ranges between 0 and 1. If R_S is close to 1, the curve fitted result is close to actual value, and vice versa. The correlation results are shown in Fig. 7. Since R_S is equal to 0.9331, the predicted results are determined to be very close to the experimental data.

In order to compare the predicted heat flux of the previous heat transfer models, the corresponding coefficients a are obtained from the curve fitting of the experimental heat transfer coefficient using the following equation:

$$h = \frac{q_m}{T_g - T_w} \quad (25)$$

where q_m is the averaged experimental instantaneous heat flux during compression and expansion strokes; and T_g and T_w are obtained from Eqs. (2) and (23), respectively. The curve fitted coefficients a of the previous models are shown in Table 2. The R_S of instantaneous heat flux and the heat transfer at cylinder head are used to evaluate the curve fitted results of previous models. The heat transfer

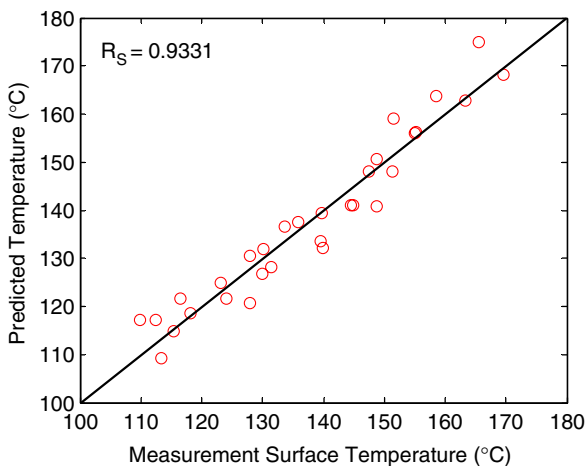


Fig. 7. Correlations between the measured and predicted T_w .

Table 2
Curve fitted results of previous models

	Original a	Fitted a	R_S of the instantaneous heat flux	R_S of the heat transfer at the cylinder head
Nusselt	5.41E-03	1.80E-02	0.8753	0.68051
Eichelberg	7.67E-03	1.20E-02	0.9383	0.7189
Annand	0.350	1.87	0.9767	0.9401
Sitkei	2.36E-04	1.30E-03	0.92375	0.77256
Hohenberg	0.130	0.760	0.9075	0.8507

at the cylinder head is obtained by integrating the instantaneous heat flux within one cycle using the cylinder head surface as the heat transfer surface. As can be seen from Table 2, of all the previous models, Annand’s model gives the best results for both instantaneous heat flux and heat transfer in the cylinder head, and is used to compare with the proposed model in the following section.

Predicted results of instantaneous heat flux using previous models at 4000 and 6000 rpm with 6 bar BMEP are shown in Figs. 8 and 9, respectively. The predicted results deviated from the experimental value, especially for the high engine speed of 6000 rpm. Although previous models have been curve fitted using the experimental data, they still cannot be widely used for all operating conditions. This might be because the previous models were proposed for large-scale engines, and the heat transfer characteristics of large-scale engines are different from that of small-scale engines.

In order to develop the proposed heat transfer model, the spark plug temperature T_{sp} is used to replace the wall temperature as in Eq. (1). It is represented as an experimental formula, which can be determined from the intake manifold pressure P_m and engine speed ω_e as

$$T_{sp} = a_{c1} - a_{c2} \cdot \omega_e - a_{c3} \cdot \omega_e^2 - a_{c4} \cdot P_m + a_{c5} \cdot P_m^2 + a_{c6} \cdot \omega_e \cdot P_m, \quad \text{unit} = ^\circ\text{C} \quad (26)$$

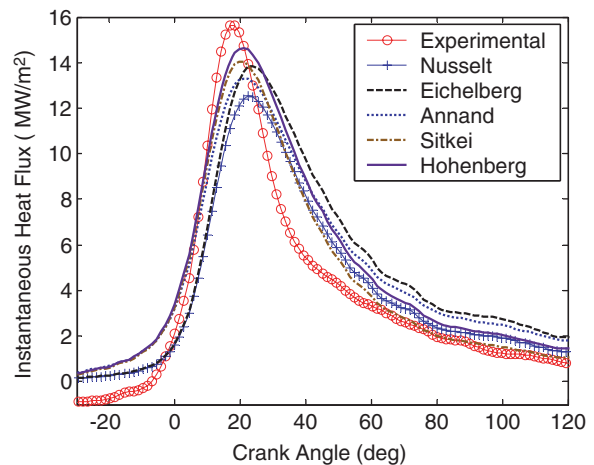


Fig. 8. Predicted heat flux using previous models at 4000 rpm with 6 bar BMEP.

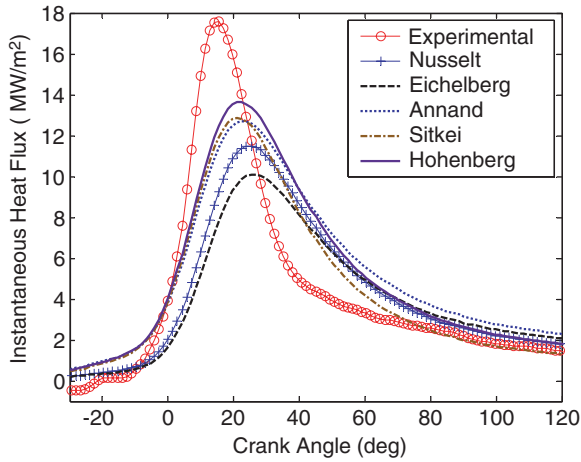


Fig. 9. Predicted heat flux using previous models at 6000 rpm with 6 bar BMEP.

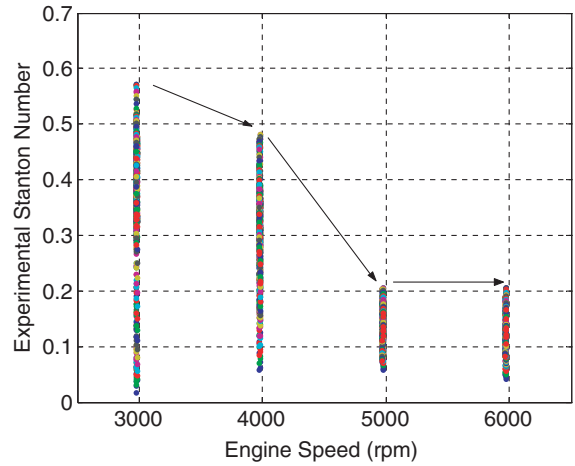


Fig. 11. Correlation of experimental Stanton number and engine speed.

where a_{ci} is the coefficient obtained from the curve fitting of experimental results and is listed in Appendix 1. Correlations between the measured and predicted T_{sp} are shown in Fig. 10. Since R_S is equal to 0.9559, the predicted result is determined to be very close to the experimental data.

In order to develop a heat transfer model for all operating conditions of the target engine, the Stanton number St is employed for the proposed model, as mentioned in Section 2.2. As can be seen from Fig. 11, the Stanton number is varied with engine speed, and presents an exponential tendency. Therefore, this paper employed an exponential function with the engine speed to represent the Stanton number, which is expressed as

$$St = 0.718 \cdot \exp(-0.145 \cdot C_m) \tag{27}$$

Correlations between the predicted and measured instantaneous heat flux are shown in Fig. 12 with $R_S = 0.9980$. Similar results for the heat transfer at the cylinder head are shown in Fig. 13 with $R_S = 0.9979$. Since the R_S of both instantaneous heat flux and heat transfer at the cyl-

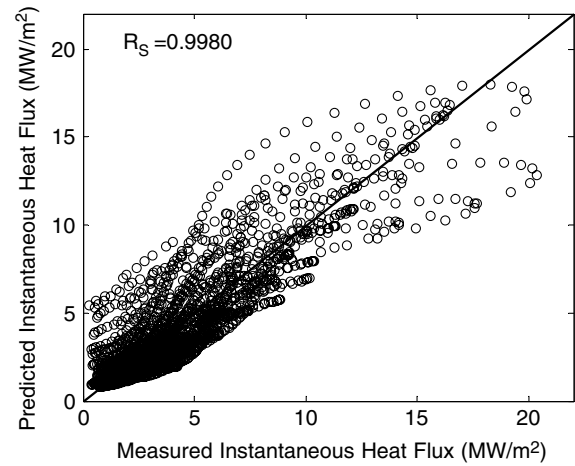


Fig. 12. Correlation between the predicted and measured instantaneous heat flux.

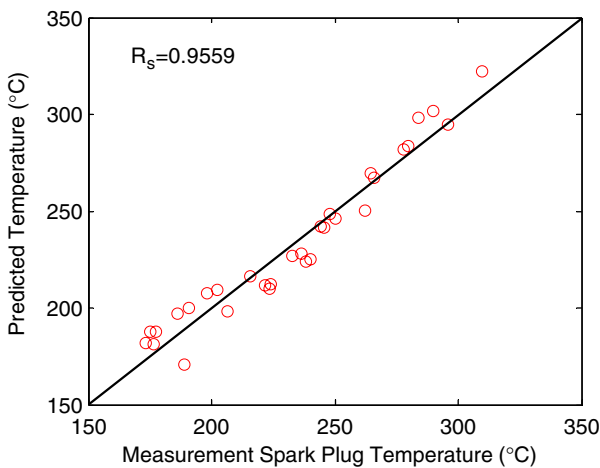


Fig. 10. Correlations between the measured and predicted T_{sp} .

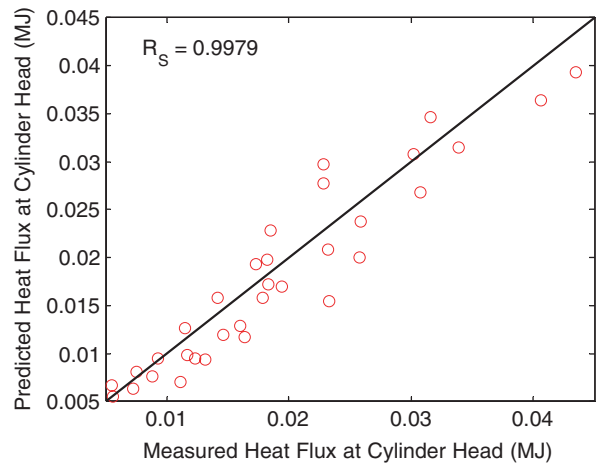


Fig. 13. Correlation between the predicted and measured heat transfer at cylinder head.

inder head are very close to 1, the predicted results of the proposed model are determined to be very close to experimental data.

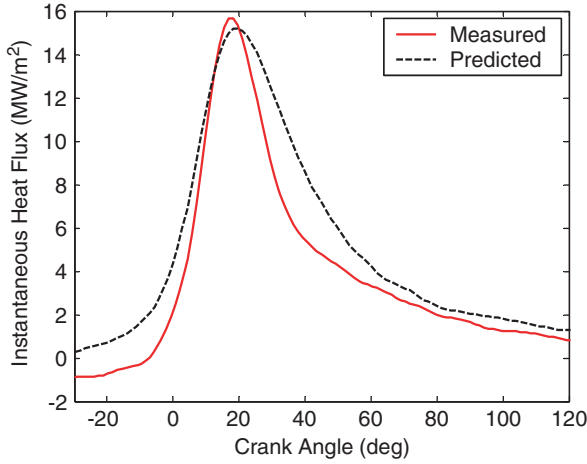


Fig. 14. Predicted and measured instantaneous heat flux at 4000 rpm with 6 bar of BMEP.

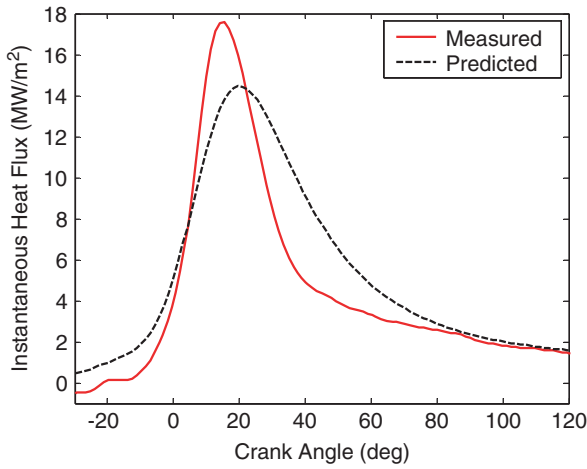


Fig. 15. Predicted and measured instantaneous heat flux at 6000 rpm with 6 bar of BMEP.

Predicted results of instantaneous heat flux using previous models at 4000 and 6000 rpm with 6 bar BMEP are shown in Figs. 14 and 15, respectively. Compared to the previous models, the predicted results of the proposed model are closer to the measured data at different engine speeds.

4. Engine model

An engine model is established with Matlab/Simulink as shown in Fig. 16 [23,24]. The charge model is a filling and

emptying model based on the one-dimensional isentropic compressible flow equation for predicting the air flow rate. It consists of non-choked and choked flow dynamics as shown in Eqs. (28) and (29), respectively.

$$\dot{m}_{ai} = \frac{C_{d,im} A_{th} P_{atm}}{\sqrt{R_a T_{atm}}} \left(\frac{P_{im}}{P_{atm}} \right)^{\frac{1}{\gamma_a}} \left\{ \frac{2\gamma_a}{\gamma_a - 1} \left[1 - \left(\frac{P_{im}}{P_{atm}} \right)^{\frac{\gamma_a - 1}{\gamma_a}} \right] \right\}^{\frac{1}{2}},$$

when $\frac{P_{im}}{P_{atm}} > \left(\frac{2}{\gamma_a + 1} \right)^{\frac{\gamma_a}{\gamma_a - 1}}$ (28)

$$\dot{m}_{ai} = \frac{C_{d,im} A_{th} P_{atm}}{\sqrt{R_a T_{atm}}} \sqrt{\gamma_a} \left(\frac{2}{\gamma_a + 1} \right)^{\frac{\gamma_a + 1}{2(\gamma_a - 1)}},$$

when $\frac{P_{im}}{P_{atm}} \leq \left(\frac{2}{\gamma_a + 1} \right)^{\frac{\gamma_a}{\gamma_a - 1}}$ (29)

where \dot{m}_{ai} is the mass airflow through the throttle body; $C_{d,im}$ is the discharge coefficient of the intake manifold; A_{th} is the cross-sectional area of the throttle body; R_a is the ideal gas constant of air; γ_a is the specific heat ratio of air; T_{atm} and P_{atm} are the temperature and pressure of the atmosphere, respectively. The intake manifold pressure P_{im} is obtained from the state equation of the ideal gas.

$$\frac{dP_{im}}{dt} = \frac{R_{air} T_{im}}{V_{im}} (\dot{m}_{ai} - \dot{m}_{ao}) \quad (30)$$

where V_{im} is the volume of the intake manifold. \dot{m}_{ao} is the mass airflow from the intake manifold into the cylinder, which can be expressed as

$$\dot{m}_{ao} = \frac{P_{im} V_d}{R_{air} T_{im} \pi} \omega \eta_v \quad (31)$$

where V_d is the displaced cylinder volume; ω is the engine speed; and η_v is the volumetric efficiency.

The combustion model can be represented using the heat release model, which is a zero-dimensional model based on the first law of thermodynamics [23,24].

$$\frac{dP_{cyl}}{d\theta} = \frac{\gamma_g - 1}{V_{cyl}} \left(\frac{dQ_{hr}}{d\theta} - \frac{dQ_{ht}}{d\theta} \right) - \frac{\gamma_g P_{cyl}}{V_{cyl}} \frac{dV_{cyl}}{d\theta} \quad (32)$$

where γ_g is the specific heat ratio of cylinder gas; P_{cyl} and V_{cyl} are the pressure and volume of the cylinder, respectively; and θ is the crank angle. The heat transfer rate is calculated from Eqs. (1), (11) and (27). The heat release rate with respect to the crank angle can be obtained from the rate of mass fraction burned as

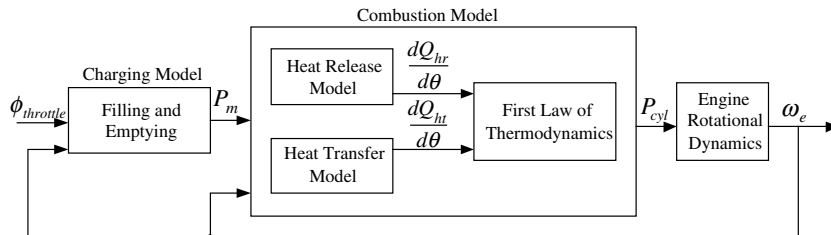


Fig. 16. Block diagram of the engine model.

$$\frac{dQ_{hr}}{d\theta} = a_1 \frac{a_2 + 1}{\theta_d} \left(\frac{\theta - \theta_0}{\theta_d}\right)^{a_2} \exp\left[-a_1 \left(\frac{\theta - \theta_0}{\theta_d}\right)^{a_2+1}\right] Q_{HV} m_f \quad (33)$$

where m_f is fuel mass injected into the cylinder; θ_d is the total combustion duration expressed in crank angle; θ_0 is the start of combustion; Q_{HV} is the heating value of fuel; a_1 and a_2 are 5 and 2, respectively [7].

5. Verification results

Experimental data of cylinder pressure is used to verify the proposed model. Since Annand’s model has the best curve fitting results of the previous models, as shown in Table 2, it is selected for comparison with the model proposed in this paper. In addition, we also investigate whether the heat transfer surface should be used with the proposed $2A_p$ or the entire surface of the combustion chamber.

The comparison of cylinder pressures at 3000 and 6000 rpm with 7 bar BMEP (full load) are shown in Figs. 17 and 18, respectively. Both figures show that the proposed model with $2A_p$ has the predicted results closest to the experimental data, especially for the low speed condition. However, if the heat transfer surface is defined as the entire surface of the combustion chamber, which is shown as Acc in Figs. 17 and 18, it results in underestimated cylinder pressure due to overestimated heat transfer rate.

The comparison of averaged R_S for the proposed model and Annand’s model at all engine operating conditions with different areas of the heat transfer surface is shown in Table 3. It is found that the proposed model with $2A_p$ has the largest R_S , i.e. the best prediction results.

In order to compare the proposed model and Annand’s model with $2A_p$ at all engine operating conditions, the dif-

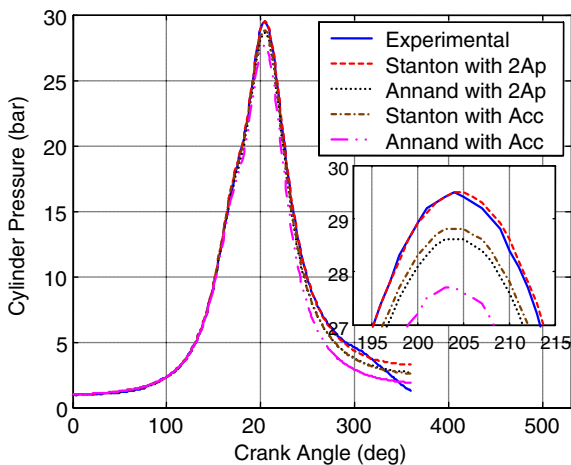


Fig. 17. Comparison of the cylinder pressure at 3000 rpm with 7 bar BMEP (full load).

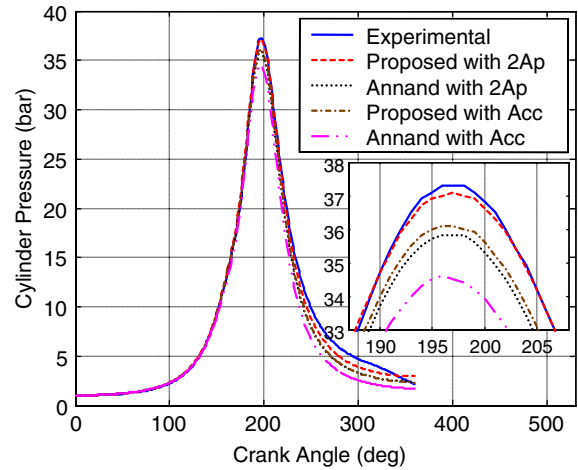


Fig. 18. Comparison of the cylinder pressure at 6000 rpm with 7 bar BMEP (full load).

Table 3
Averaged R_S of the cylinder pressure at all engine operating conditions

	Proposed with $2A_p$	Annand with $2A_p$	Proposed with Acc	Annand with Acc
Averaged R_S	0.949	0.862	0.851	0.829

Table 4
 ΔR_S of the cylinder pressure

ω_e (rpm)	BMEP						
	1 bar	2 bar	3 bar	4 bar	5 bar	6 bar	7 bar
3000	-0.046	0.023	0.049	0.084	0.095	0.090	0.042
4000	-0.008	0.197	0.140	0.016	-0.006	0.017	0.034
5000	0.167	0.221	0.155	0.076	0.065	-0.014	0.021
6000	0.162	0.245	0.303	0.107	0.074	0.021	0.106

Note: negative mean value = -0.018; positive mean value = 0.105.

ference between the R_S of the proposed model $R_{S,Proposed}$ and the R_S of the Annand’s model $R_{S,Annand}$ is defined as

$$\Delta R_S = R_{S,Proposed} - R_{S,Annand} \quad (34)$$

If ΔR_S is positive, the proposed model performs better than Annand’s model, and vice versa. The results of ΔR_S at all operating conditions are shown in Table 4. As can be seen from Table 4, the proposed model has closer prediction results than Annand’s model at most engine operation conditions with a positive mean value of 0.105, which is about twice the magnitude of the negative mean value of -0.018 at the other engine operating conditions.

6. Conclusions

The heat transfer models proposed by Nusselt, Eichelberg, Annand, Sitkei, and Hohenberg are not suitable for small-scale SI engines because they were developed

primarily for diesel engines and large-scale SI engines. After curve fitting of the experimental data of a 125 cm³ air-cooled SI engine, Annand's model has the closest prediction results of the previous models. However, it still cannot be widely used for all operation conditions, perhaps because the previous models were proposed for large-scale engines, and the heat transfer characteristics of large-scale engines are different from that of the small-scale ones. In order to develop a heat transfer model suitable for small-scale SI engines, a model using the Stanton number, which is much simpler but yet accurate enough, is proposed in this paper. The area of heat transfer surface is defined as two times the piston area, i.e. $2A_p$, for the proposed model. Experimental data for cylinder pressure were used to verify the proposed model. The results show that the proposed model has better prediction results than the Annand's model at most engine operation conditions. It was also found that the prediction results of the cylinder pressure using $2A_p$ as the heat transfer surface is more accurate than that using the entire surface of the combustion chamber.

Acknowledgement

The authors would like to thank the Industrial Technology Research Institute (ITRI, Taiwan) for providing the experimental data and the National Science Council (NSC, Taiwan) for financial support (NSC-93-2212-E-027-009).

Appendix 1

See Table A.1.

Table A.1
Coefficients of T_c and T_w

a_{w1}	1408.7	a_{c1}	1176.2
a_{w2}	9.3021	a_{c2}	2.4074
a_{w3}	4.7205×10^{-3}	a_{c3}	0.017601
a_{w4}	2640.1	a_{c4}	2603.8
a_{w5}	1423.4	a_{c5}	1540.4
a_{w6}	9.8922	a_{c6}	6.3406

Appendix 2

See Tables A.2–A.5.

Table A.2
 R_S of the proposed model with $2A_p$

ω_c (rpm)	BMEP						
	1 bar	2 bar	3 bar	4 bar	5 bar	6 bar	7 bar
3000	0.895	0.851	0.962	0.942	0.903	0.876	0.971
4000	0.772	0.960	0.986	0.988	0.994	0.999	0.995
5000	0.929	0.932	0.928	0.973	0.984	0.974	0.998
6000	0.942	0.936	0.989	0.954	0.971	0.973	0.992

Mean = 0.949.

Table A.3
 R_S of the Annand's model with $2A_p$

ω_c (rpm)	BMEP						
	1 bar	2 bar	3 bar	4 bar	5 bar	6 bar	7 bar
3000	0.941	0.828	0.912	0.858	0.808	0.787	0.929
4000	0.780	0.763	0.846	0.971	0.999	0.982	0.961
5000	0.762	0.711	0.773	0.897	0.919	0.988	0.976
6000	0.780	0.691	0.686	0.847	0.898	0.952	0.886

Mean = 0.862.

Table A.4
 R_S of the proposed model with the entire surface of the combustion chamber

ω_c (rpm)	BMEP						
	1 bar	2 bar	3 bar	4 bar	5 bar	6 bar	7 bar
3000	0.768	0.850	0.826	0.873	0.976	0.961	0.900
4000	0.796	0.697	0.716	0.819	0.867	0.871	0.950
5000	0.746	0.728	0.787	0.854	0.879	0.956	0.960
6000	0.787	0.759	0.765	0.883	0.921	0.973	0.962

Mean = 0.851.

Table A.5
 R_S of the Annand's model with the entire surface of the combustion chamber

ω_c (rpm)	BMEP						
	1 bar	2 bar	3 bar	4 bar	5 bar	6 bar	7 bar
3000	0.815	0.887	0.877	0.950	0.921	0.856	0.867
4000	0.897	0.690	0.674	0.793	0.871	0.881	0.889
5000	0.797	0.673	0.692	0.763	0.816	0.909	0.932
6000	0.961	0.874	0.644	0.724	0.792	0.890	0.886

Mean = 0.829.

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